

# gold casino

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urce (transmitter) and reflected from objects in the scene.&lt;/span&gt; &lt;spa  
n&gt;The reflected light is detected by the system receiver&lt;/span&gt; and the  
time of flight (TOF) is used to develop a distance map of the objects in the sc  
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t;div&gt;&lt;div&gt;&lt;div&gt;&lt;div&gt;&lt;span&gt;The object-wise feature ex  
tractors project LiDAR point clouds into 2D representations and generate the obj  
ect proposals using 2D networks&lt;/span&gt;. Then, they regress the region prop  
osals to predict the 3D bounding boxes.&lt;/div&gt;&lt;/div&gt;&lt;/div&gt;&lt;/