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In LiDAR, laser light is sent from a source (transmitter) and reflected from objects in the scene. The reflected light is detected by the system receiver and the time of flight (TO)  $T = \frac{2R}{c}$

What is LiDAR and How Does it Work? - Synopsys : glossary : what-is-lidar  
data-ved="2ahUKewjvvnvG4-s-DAXXpKQIHcOwBe4QFnoECAEQBg" href="{href}"></span></div><span>What is LiDAR and How Does it Work? - Synopsys : glossary : what-is-lidar</span></div><span>synopsys : glossary : what-is-lidar</span></div><a data-ved="2ahUKewjvvnvG4-s-DAXXpKQIHcOwBe4Qzmd6BAGBEAc" href="{href}">O O bet365</a></span></div></div>

The object-wise feature extractors project LiDAR point clouds into 2D representations and generate the object proposals using 2D networks. Then, they regress the region proposals to predict the 3D bounding boxes.

A Survey on Deep-Learning-Based LiDAR 3D Object Detection for ...</span></div><span>mdpi : ...</span></div></span></div><a data-ved="2ahUKewjvvnvG4-s-DAXXpKQIHcOwBe4Qzmd6BAGBEA4" href="{href}">O O bet365</a></span></div></div>

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